

# Finding Large Subgraphs

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# The maximum subgraph problem

The maximum subgraph problem for a Graph property  $\Pi$  asks:

Given a graph  $G$ , find a subgraph  $H$  of  $G$  satisfying property  $\Pi$  that has the maximum number of edges.

# The maximum induced subgraph problem

The maximum induced subgraph problem for a Graph property  $\Pi$  asks:

Given a graph  $G$ , find an induced subgraph  $H$  of  $G$  satisfying property  $\Pi$  that has the maximum number of vertices.

In other words, find the minimum number of vertices to remove from  $G$  such that the remaining subgraph satisfies the property  $\Pi$ .

# Graph Properties

The following **Graph properties** are commonly considered:

- Forest (cycles are forbidden)
- Bipartite subgraph (odd cycles are forbidden)
- Planar subgraph ( $\{K_5, K_{3,3}\}$ -minors are forbidden)
- Complete subgraph  
There is no difference between induced and non-induced versions for this.
- Independent set  
This is meaningful only for the induced version.

All these properties are **hereditary**, every subgraph of a graph with property  $\Pi$  also has property  $\Pi$ .

Connectedness is an example of a property that is not hereditary.

# Finding Large Subgraphs

Except for the largest Forest subgraph problem, all these largest subgraph problems are NP-hard.

In case of the largest induced subgraph problem, [Lewis and Yannakakis \(1980\)](#) showed that:

The largest induced subgraph problem is NP-hard for every non-trivial hereditary property.

What about approximate solutions?

# Approximation Algorithms

Algorithm  $\mathcal{A}$  for a maximization problem  $MAX$  achieves an **approximation factor**  $\alpha$  if

for all inputs  $G$ , we have:  $\frac{\mathcal{A}(G)}{OPT(G)} \leq \alpha$ ,

where  $\mathcal{A}(G)$  is the value of the output generated by the algorithm  $\mathcal{A}$ ,  
and  $OPT(G)$  is the optimal value.

A  **$\alpha$ -approximation algorithm** for  $MAX$  is a polynomial time algorithm that achieves the approximation factor  $\alpha$ .

To show  $\mathcal{A}$  achieves approximation factor  $\alpha$ , we typically show that:  $\mathcal{A}(G) \geq L$  and  $OPT(G) \leq U$ , so  $\alpha \geq L/U$ .

# Approximation Algorithms for Large Subgraphs

For example

for the **largest bipartite subgraph problem**:

**Goemans and Williamson (1995)**: 0.878-approximation algorithm

**Hastad (1997)**: If  $P \neq NP$  then there is no  $\alpha$ -approximation algorithm for any  $\alpha > 0.941$ .

for the **largest clique subgraph problem**:

**Feige (2005)**:  $O(n(\log \log n)^2 / (\log n)^3)$ -approximation algorithm

**Feige et al. (1996)**: It is hard to approximate MAX-Clique for any constant factor.

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# Approximation Algorithms for Large Induced Subgraphs

**Lund and Yannakakis (1993)**: It is hard to approximate the largest induced subgraph problem for any hereditary property.

Comparatively, very little research has been done on approximation algorithms for these problems.

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For the **maximum induced bipartite subgraph problem**:  
Some results for very special classes of graphs -

**Zhu (2009)**:  $5/7$  approximation factor algorithm over triangle-free subcubic graphs.

**Addario-Berry (2006)**: Some results for  $i$ -triangulated graphs and clique-separable graphs.

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# Approximation Algorithms for Large Induced Subgraphs

For the maximum induced Planar subgraph problem:

**Calinescu et al. (1998)**: There exists an  $\epsilon > 0$  such that there is no  $1 - \epsilon$ - approximation algorithm unless  $P = NP$ .

**Edward and Farr (2007)**:  $3/(d + 1)$ -approximation algorithm on graphs of average degree at most  $d \geq 4$ , [in fact they find an induced series-parallel subgraph (more about these later)].

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Till 1990's a number of algorithms were studied but none gave an approximation ratio better than  $1/3$ , which can be trivially achieved by the Spanning Tree algorithm.

$$ST(G) = n - 1 \text{ and } OPT(G) \leq 3n - 6$$

Calinescu et al. (1998):  $4/9$ -approximation algorithm, which is still the best known.

In fact, this algorithm generates an outerplanar subgraph (which gives a  $2/3$ -approximation algorithm for the maximum outerplanar graph problem).

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# Large Series-Parallel Subgraphs

**Planar graphs** are characterized as having no  $\{K_5, K_{3,3}\}$  minors or subdivisions.

**Outerplanar graphs** are characterized as having no  $\{K_4, K_{2,3}\}$  minors or subdivisions.

How about subgraphs with no  $K_4$  minors or subdivisions?  
These will be planar but not outerplanar.

These are **Series-Parallel graphs**.

$H$  is a **minor** of  $G$  if a graph isomorphic to  $H$  can be obtained from  $G$  by contracting some edges, deleting some edges, and deleting some isolated vertices.

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# Large Series-Parallel Subgraphs

Series-Parallel graphs are characterized as:

- No  $K_4$  minor or subdivision.
- Arises from a forest by adding parallel edges, subdividing edges, and at the end removing any parallel edges to keep the graph simple.
- tree width  $\leq 2$  (subgraph of 2-tree).

# Large Series-Parallel Subgraphs

The maximum Series-Parallel subgraph problem is *NP*-hard.

Since, the number of edges of a Series-Parallel graph on  $n$  vertices is bounded above by  $2n - 3$ , the spanning tree algorithm gives a  $1/2$ -approximation algorithm.

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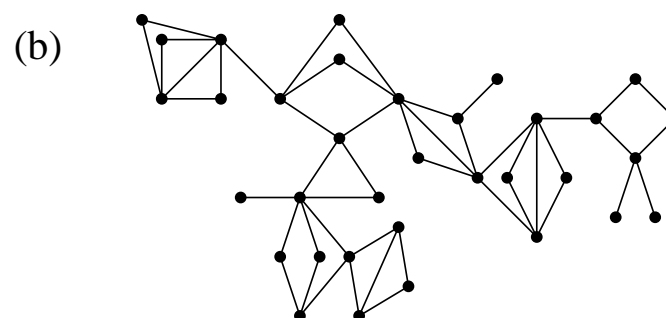
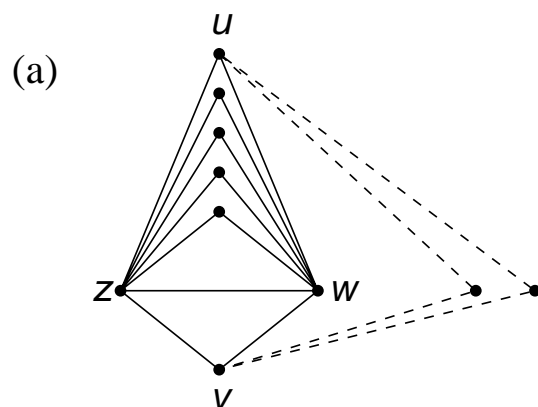
Can we do better?

# New Results

Calinescu, Fernandes, K. (2009): 7/12 approximation algorithm for the maximum Series-Parallel subgraph problem.

The output is a **spruce structure**: a graph each of whose blocks is either a spruce or an edge.

A **spruce** consists of two *base* vertices and at least one *tip* vertex, in which each tip vertex is adjacent to exactly the two base vertices.



# New Results

Calinescu, Fernandes, K. (2009): The maximum spruce structure would give a  $2/3$  approximation for the maximum Series-Parallel subgraph.

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# New Ideas

## Comparison with previous algorithms for Planar subgraphs:

- Unlike earlier algorithms, the subgraph we generate is not a tree or an outerplanar graph.
- Unlike earlier algorithms, we have to allow blocks of unbounded size in our subgraph.
- Unlike earlier algorithms, we sometimes have to shrink or throw away previously selected blocks.

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Unlike earlier algorithms, we have to allow blocks of unbounded size in our subgraph.

If the input graph is a *complete spruce* (spruce with an edge between the base vertices) with  $n - 2$  tips, then any algorithm that only generates blocks of size at most  $k$  would result in an output with a total  $n + k - 3$  edges.

With large  $n$  and fixed  $k$ , this is only a  $1/2$ -approximation.

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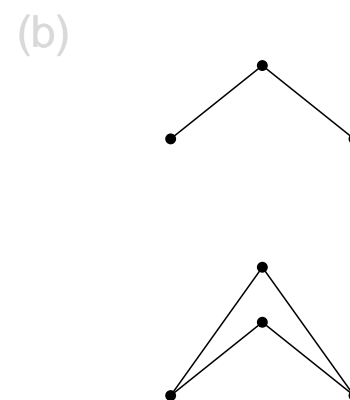
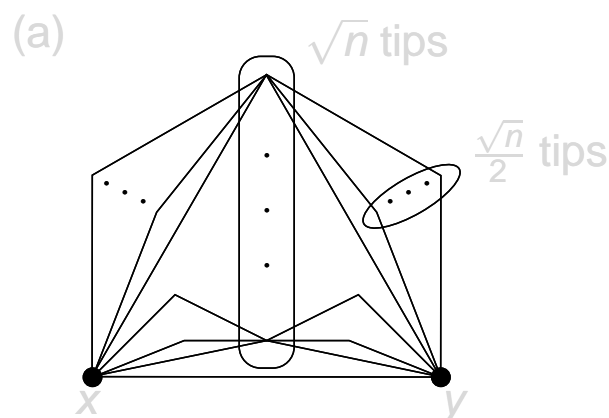
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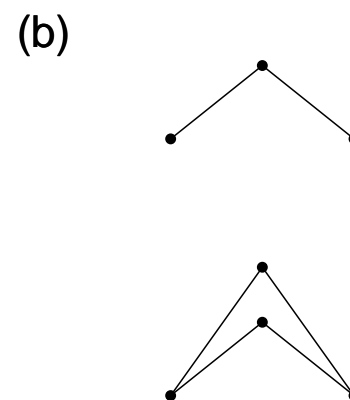
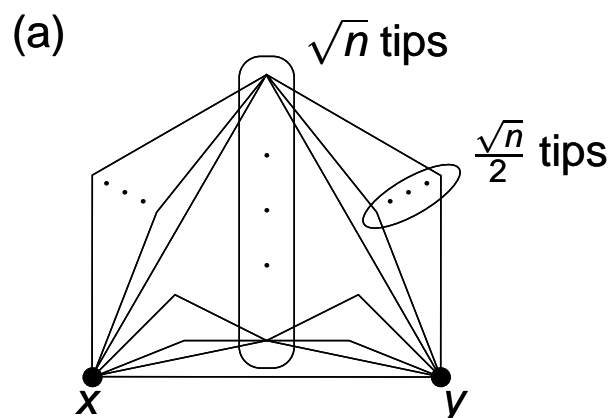
The optimum has  $n$  vertices and  $2n-3$  edges.

A spruce with base vertices  $x$  and  $y$  and  $\sqrt{n}$  tips. For each of its tips  $v$ , there are two complete spruces, one with base vertices  $x$  and  $v$ , and the other with base vertices  $v$  and  $y$ , each with  $\sqrt{n}/2$  tips.

If an algorithm mistakenly (or greedily) selects the spruce with base vertices  $x$  and  $y$ , then it cannot add any more spruces and it ends up with about  $n + \sqrt{n}$  edges — asymptotically not better than a  $1/2$ -approximation.

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# The Algorithm - Preliminaries

$gain(S) :=$  cyclomatic number

For complete spruces,  $gain$  is the number of tips;

adjusted gain  $\widehat{gain} := gain$ .

For incomplete spruces,  $gain$  is one less than the number of

tips; adjusted gain  $\widehat{gain} := gain - 1$ .

# The Algorithm - Underlying Idea

We maintain  $Q$ , a collection of spruces.

**What we add:** Spruces with tips that are isolated vertices.

Let  $v_1, v_2, \dots, v_k$  be all vertices isolated in  $Q$  that are adjacent in  $G$  to both  $x$  and  $y$ .

If  $k \geq 1$ , let  $S_Q(x, y)$  be the spruce with base vertices  $x$  and  $y$ , tips  $v_1, v_2, \dots, v_k$ , and the edge  $xy$  if it exists in  $G$ . Add  $S_Q(x, y)$  to  $Q$ .

**What do we remove:** For each component  $C$  of  $Q$ , the algorithm keeps a *weighted tree*  $T_C$  whose vertex set is  $V(C)$  and edge set is as follows: For each spruce  $S$  in  $C$  with base vertices  $x$  and  $y$ , and tips  $v_1, v_2, \dots, v_k$ , there is an edge  $xy$  with weight  $\widehat{\text{gain}}$  in  $T_C$  and edges  $xv_i$  with weight 1 for  $i = 1, \dots, k$ .

$\text{index}_Q(x, y)$  is an edge in  $T_C$  of minimum weight in the path in  $T_C$  from  $x$  to  $y$ . Let  $x'$  and  $y'$  be the endpoints of  $\text{index}_Q(x, y)$ , and  $C$  be the component of  $Q$  containing  $x, x', y$ , and  $y'$ . Let  $S'$  be the spruce in  $Q$  containing  $x'$  and  $y'$ . If  $x'$  and  $y'$  are the base vertices of  $S'$ , then remove  $S'$  from  $Q$ .



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# The Algorithm

CONSTRUCT-SPRUCE-STRUCTURE ( $G$ )

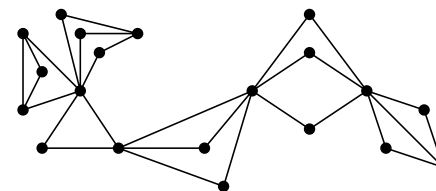
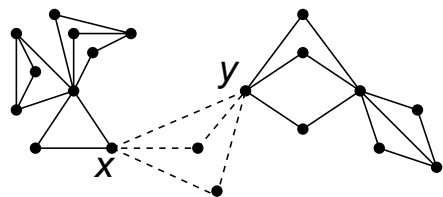
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1    $Q \leftarrow \emptyset$ 
2   while there are  $x$  and  $y$  such that  $S_Q(x, y)$  is defined
      and  $\widehat{gain}(S_Q(x, y)) > w(index_Q(x, y))$  do
3     if  $index_Q(x, y)$  is undefined
4       then  $Q \leftarrow Q \cup \{S_Q(x, y)\}$ 
5       else let  $x'$  and  $y'$  be the endpoints of  $index_Q(x, y)$ 
6         let  $S'$  be the spruce in  $Q$  containing  $x'$  and  $y'$ 
7          $Q \leftarrow Q \setminus \{S'\} \cup \{S_Q(x, y)\}$ 
8         if  $x'$  or  $y'$  is a tip of  $S'$ 
9           then let  $z$  be between  $x', y'$ , a tip of  $S'$ 
10          let  $\{e, f\}$  be the edges of  $S'$  touching  $z$ 
11           $S \leftarrow S' - \{e, f\}$ 
12          if  $S$  is not degenerate nor single edge
13            then  $Q \leftarrow Q \cup \{S\}$ 
14  add bridges to  $Q$  to obtain a connected spanning subgraph of
15   $G$ 
15  return  $Q$ 

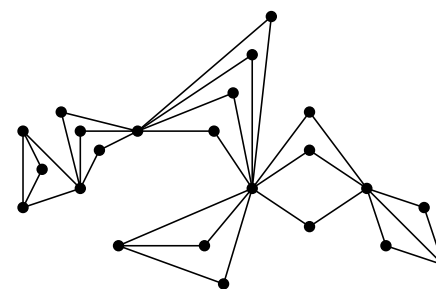
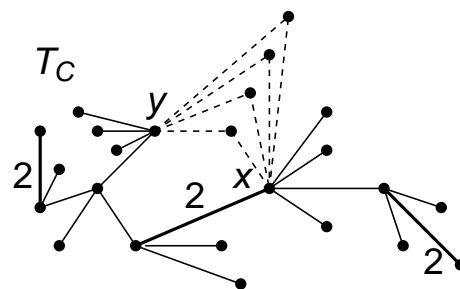
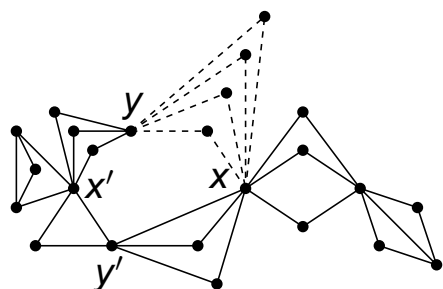
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# Local improvement examples

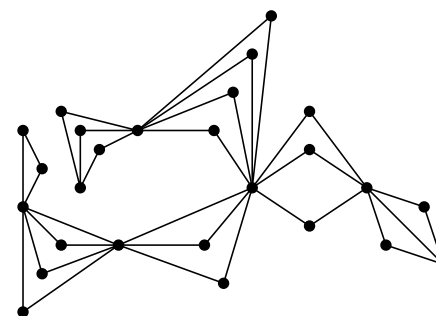
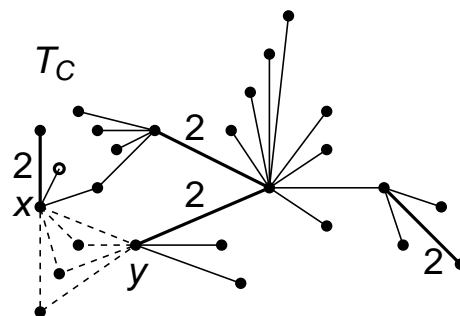
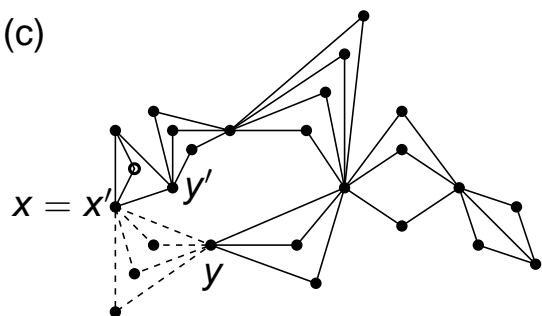
(a)



(b)



(c)



# Running Time Analysis

If  $gain(Q)$  increased in every iteration, then it would have been easy to conclude that the algorithm runs a polynomial number of iterations. The gain of  $Q$  never decreases and, in the iterations in which the gain of  $Q$  is same, the number of components increases.

Define  $\Phi(Q) = 3 gain(Q) + c(Q)$ , where  $c(Q)$  is the number of components of  $Q$  when  $Q$  is seen as a spanning subgraph of  $G$ .

We prove: Every iteration of the algorithm increases the parameter  $\Phi$ .

$gain(Q) \leq (2n-3) - (n-1) = n-2$ ,  
so  $\Phi(Q)$  is bounded by  $3(n-2) + n = 4n-6$ .

Each iteration can be easily implemented in polynomial time:

$O(n^2)$  pairs  $x, y$  for which  $S_Q(x, y)$  must be computed and, if possible, used in updating  $Q$ .

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# Approximation ratio ideas - to beat $1/2$

- If significantly many vertices in our structure, we win.
- If OPT has significantly less than  $2n$  edges, we win.
- If none of the above, the spruces of OPT have significant  $\widehat{gain}$ .

# Approximation ratio ideas - to beat $1/2$

From  $OPT$ , construct weighted Series Parallel graph with  $\widehat{gain}$  on edges.

Compare to our weighted forest.

We have a maximum spanning forest in the union of the two graphs!

Thus our  $\widehat{gain}$  is  $1/2$  of what that of  $OPT$ .

Therefore we have significant  $\widehat{gain}$ .



# New Questions

- **Weighted maximum Series-Parallel subgraph problem.**
- Maximum induced Series-parallel subgraph problem.
- For fixed  $r$ , maximum  $K_r$ -minor-free subgraph problem.
- In particular, maximum  $K_5$ -minor-free subgraph problem.  
Number of edges in such a graph are  $\leq 3n - 6$ .  
Also, the structural characterization is known - constructed from copies of planar graphs and Wagner's graph by gluing over  $k$ -cliques for  $k \leq 3$ .
- For fixed  $r$ , maximum subgraph of tree width  $\leq r$ .
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Also, such graphs have no minors from  $\{K_5, \text{Wagner}, \text{two other graphs}\}$ .

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