

# Adaptive Quasi-Monte Carlo Where Each Integrand Value Depends on All Data Sites: the American Option

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# Outline

- ▶ American Options
- ▶ Quasi-Monte Carlo Cubatures
- ▶ The Challenge
- ▶ Improving Cubature Efficiency
- ▶ Conclusions and Future Work



# Outline

- ▶ **American Options**—The American option and the Longstaff and Schwartz (2001) pricing method.
- ▶ Quasi-Monte Carlo Cubatures
- ▶ The Challenge
- ▶ Improving Cubature Efficiency
- ▶ Conclusions and Future Work



# The American Put Option

Important parameters:

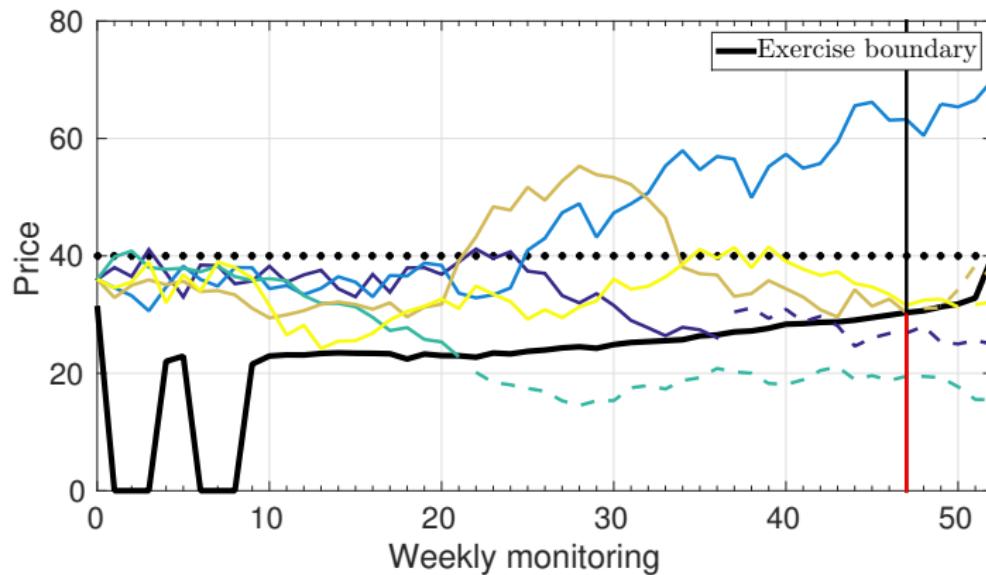
- ▶ Strike price  $K$
- ▶ Maturity  $T$
- ▶ Exercise time  $t \in [0, T]$
- ▶ Payoff  $\max(K - S(t), 0)$

For our examples we will use:

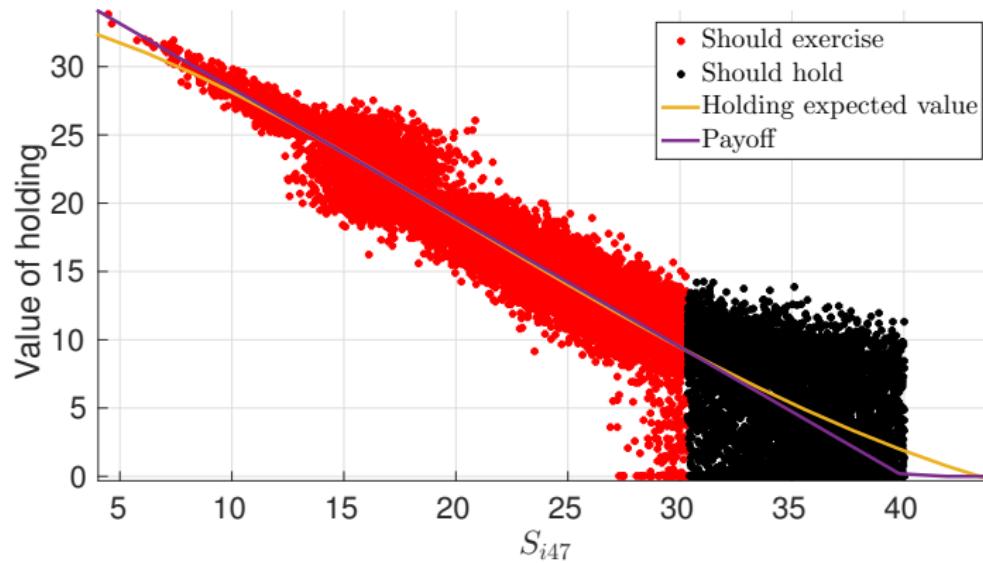
- ▶  $K = 40$
- ▶  $T = 1$  year
- ▶ Weekly monitoring,  $[1/52, 2/52, \dots, 1]$
- ▶ Geo. Brownian motion with  $S_0 = 36$ ,  $r = 6\%$ , and  $\sigma = 50\%$



# The Longstaff and Schwartz (2001) Method



## Regression at Week $j = 47$



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# Low Discrepancy Sequences

Consider an embedded sequence in base  $b$ ,

$$\mathcal{P}_0 = \{\mathbf{0}\} \subset \cdots \subset \mathcal{P}_m = \{\mathbf{x}_i\}_{i=0}^{b^m} \subset \cdots \subset \mathcal{P}_\infty = \{\mathbf{x}_i\}_{i=0}^\infty.$$

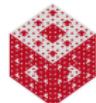
Each  $\mathcal{P}_m$  forms a group:

- ▶ Digital nets

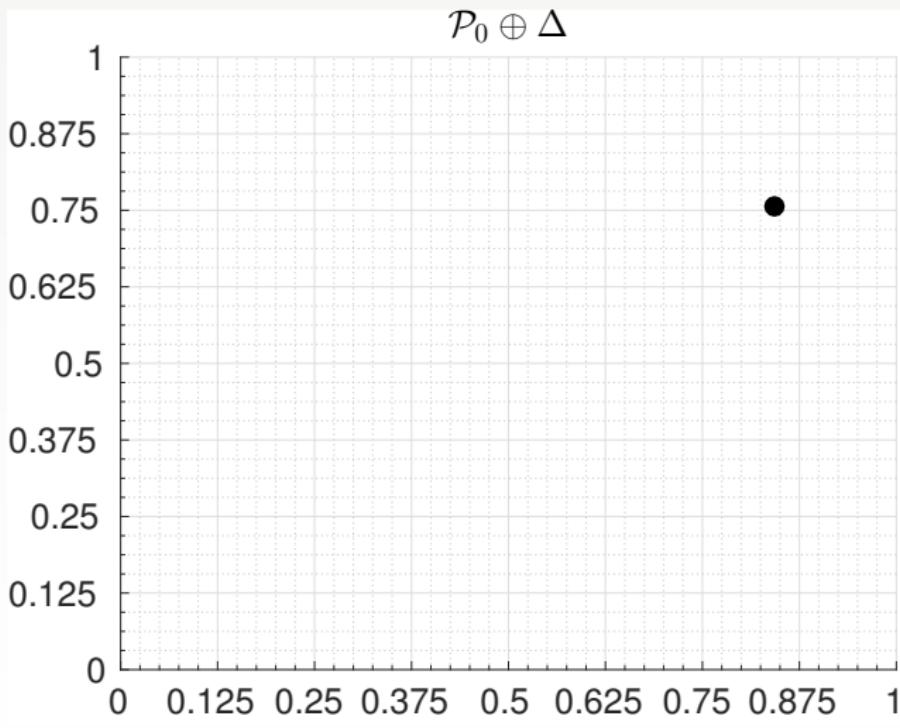
$$\mathbf{x} \oplus \mathbf{t} = \left( \sum_{\ell=1}^{\infty} [(x_{j\ell} + t_{j\ell}) \bmod b] b^{-\ell} \pmod{1} \right)_{j=1}^d.$$

- ▶ Rank-1 lattices

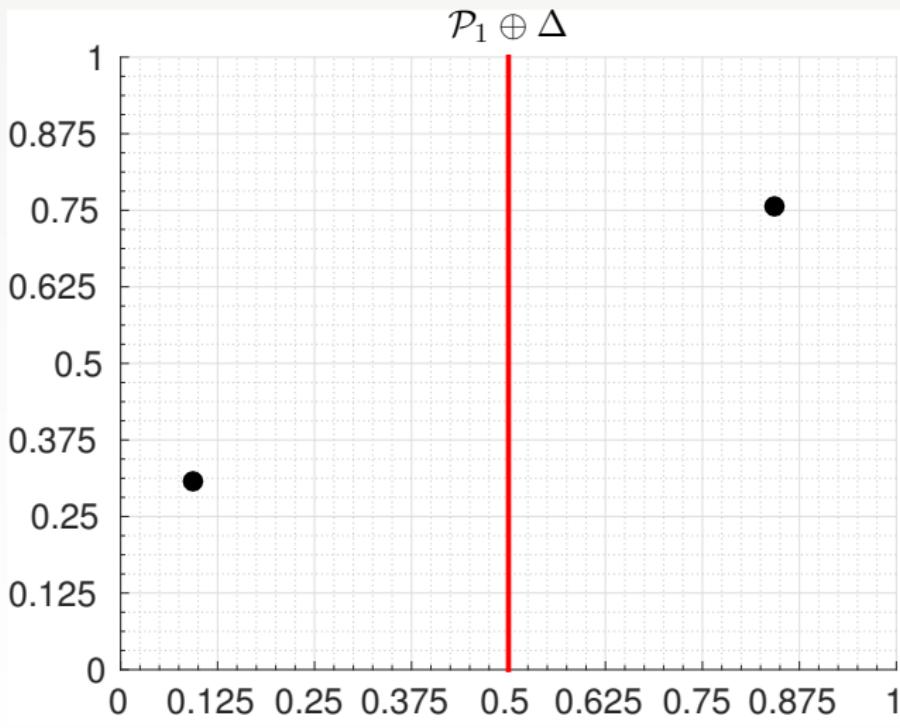
$$\mathbf{x} \oplus \mathbf{t} = (\mathbf{x} + \mathbf{t}) \bmod 1.$$



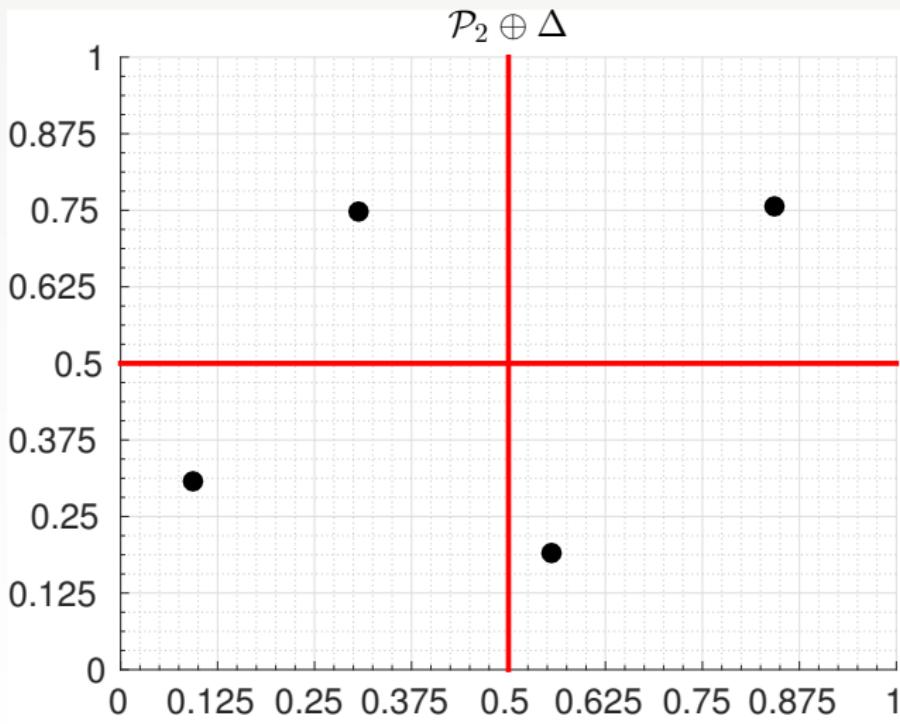
# Scrambled and Digitally Shifted Sobol' Sequence



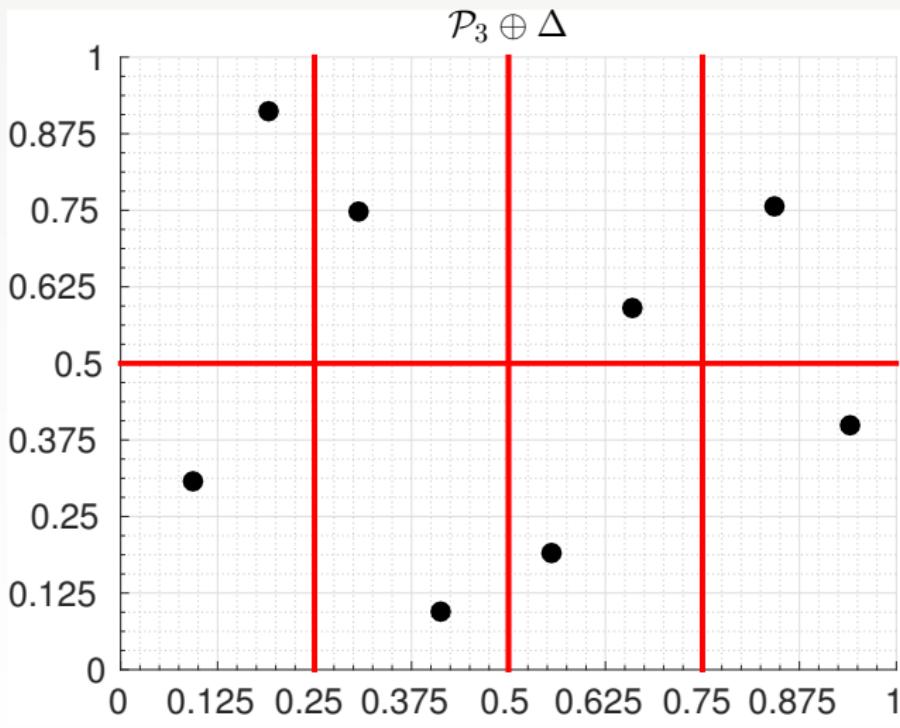
# Scrambled and Digitally Shifted Sobol' Sequence



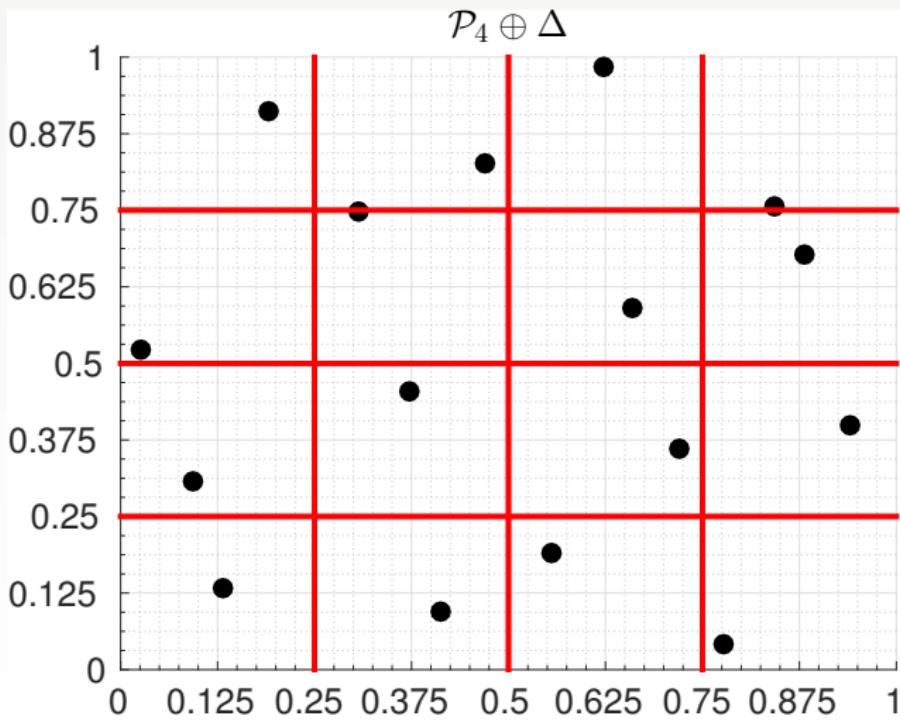
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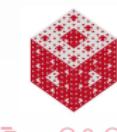
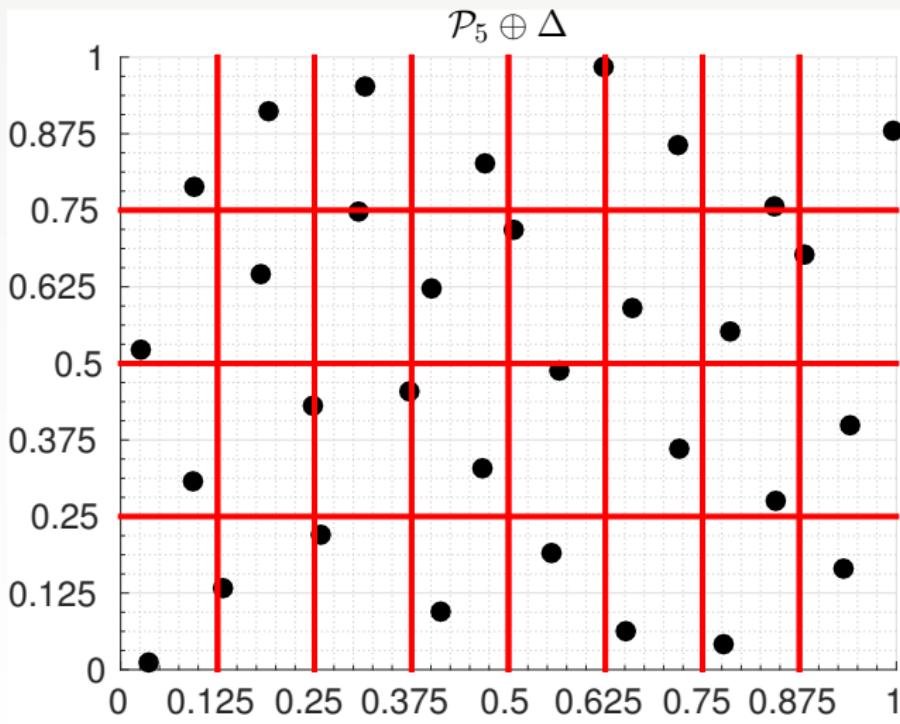
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# Scrambled and Digitally Shifted Sobol' Sequence

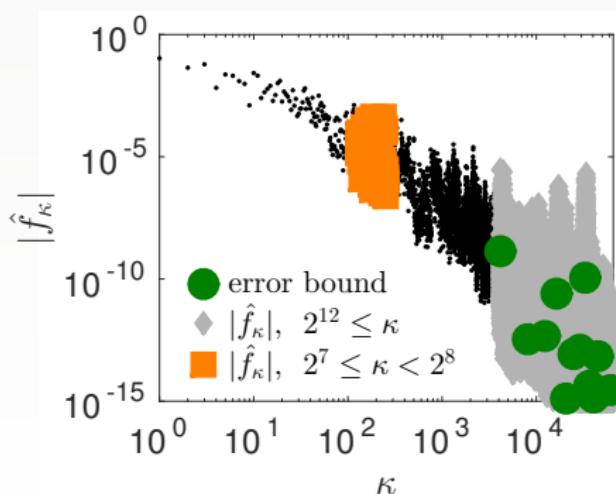


# Scrambled and Digitally Shifted Sobol' Sequence



# Adaptive Algorithm for $f \in \mathcal{C}$

$$\left| \int_{[0,1)^d} f(\mathbf{x}) d\mathbf{x} - \frac{1}{|\mathcal{P}_m|} \sum_{\mathbf{x} \in \mathcal{P}_m} f(\mathbf{x}) \right| \leq \overbrace{\sum \bullet}^{\text{Dual net/lat Fourier coef}} \leq \mathfrak{C}(r, m) \sum_{\kappa=\lfloor b^{m-r-1} \rfloor}^{b^{m-r}-1} |\tilde{f}_{m,\kappa}| \stackrel{\text{Want}}{\leq} \varepsilon$$



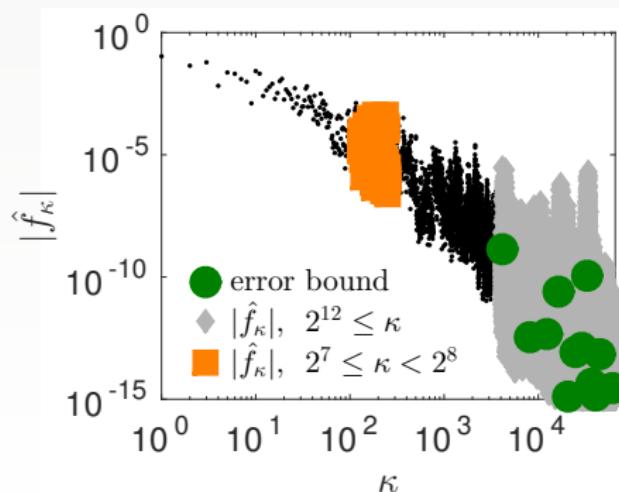
But we

- ▶ Do not want to assume that  $\bullet$  decay at a given rate.
- ▶ We cannot get  $\bullet$  from data.



## Adaptive Algorithm for $f \in \mathcal{C}$

$$\left| \int_{[0,1)^d} f(\mathbf{x}) d\mathbf{x} - \frac{1}{|\mathcal{P}_m|} \sum_{\mathbf{x} \in \mathcal{P}_m} f(\mathbf{x}) \right| \leq \overbrace{\sum_{\kappa=1}^{b^m-1} \bullet}^{\text{Dual net/lat Fourier coef}} \leq \mathfrak{C}(r, m) \sum_{\kappa=\lfloor b^{m-r-1} \rfloor}^{b^m-1} |\tilde{f}_{m,\kappa}| \stackrel{\text{Want}}{\leq} \varepsilon$$



$$\mathcal{C} = \left\{ \sum \text{orange} \text{ bounds} \quad \sum \text{grey} \text{ bounds} \quad \sum \text{green} \text{ bounds} \right\}$$



# Automatic Algorithm

We choose an initial number of points  $b^{m_0}$ . Then,

**Step 1** Generate  $\{y_i\}_{i=0}^{b^{m_0}-1} = \{f(\mathbf{x}_i)\}_{i=0}^{b^{m_0}-1}$  and compute its discrete Fourier/Walsh coefficients.

**Step 2** Estimate the error bound. If it is smaller than  $\varepsilon$ , STOP.

**Step 3** Otherwise, set  $m = m_0 + 1$ .

**Step 3.1** Generate  $\{y_i\}_{i=b^{m-1}}^{b^m-1}$ , and update the discrete Fourier/Walsh transform.

**Step 3.2** Update the error bound. If it is smaller than  $\varepsilon$ , STOP.

**Step 3.3** Increment  $m$  by one, and go to Step 3.1.



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# Updating the Function Values

The American option payoff computed according to the Longstaff and Schwartz (2001) method is **not a regular function** over  $[0, 1]^d$ :

$$\text{payoff}_i = f(\mathbf{x}_i) \quad \text{becomes} \quad \{\text{payoff}_i\}_{i=0}^{b^m-1} = f\left(\{\mathbf{x}_i\}_{i=0}^{b^m-1}\right).$$



# Former Automatic Algorithm

We choose an initial number of points  $b^{m_0}$ . Then,

**Step 1** Generate  $\{\text{payoff}_i\}_{i=0}^{b^{m_0}-1} = \{f(\boldsymbol{x}_i)\}_{i=0}^{b^{m_0}-1}$  and compute its discrete Fourier/Walsh coefficients.

**Step 2** Estimate the error bound. If it is smaller than  $\varepsilon$ , STOP.

**Step 3** Otherwise, set  $m = m_0 + 1$ .

Step 3.1 Generate  $\{\text{payoff}_i\}_{i=b^{m-1}}^{b^m-1}$ , and update the discrete Fourier/Walsh transform.

Step 3.2 Update the error bound. If it is smaller than  $\varepsilon$ , STOP.

Step 3.3 Increment  $m$  by one, and go to Step 3.1.



# New Automatic Algorithm

We choose an initial number of points  $b^{m_0}$ . Then,

**Step 1** Generate  $\{\text{payoff}_i\}_{i=0}^{b^{m_0}-1} = f(\{\boldsymbol{x}_i\}_{i=0}^{b^{m_0}-1})$  and compute its discrete Fourier/Walsh coefficients.

**Step 2** Estimate the error bound. If it is smaller than  $\varepsilon$ , STOP.

**Step 3** Otherwise, set  $m = m_0 + 1$ .

Step 3.1 Generate  $\{\text{payoff}_i\}_{i=0}^{b^m-1} = f(\{\boldsymbol{x}_i\}_{i=0}^{b^m-1})$ , and recompute the discrete Fourier/Walsh coeff.

Step 3.2 Update the error bound. If it is smaller than  $\varepsilon$ , STOP.

Step 3.3 Increment  $m$  by one, and go to Step 3.1.



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- ▶ **Improving Cubature Efficiency**—Techniques that improve the computational cost.
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## Control Variates Introduction

If  $I(g) = \int_{[0,1)^d} g(\boldsymbol{x}) d\boldsymbol{x}$  is known, then

$$\int_{[0,1)^d} f(\boldsymbol{x}) d\boldsymbol{x} = \int_{[0,1)^d} f(\boldsymbol{x}) + \beta(I(g) - g(\boldsymbol{x})) d\boldsymbol{x},$$

and, based on our cubatures, we choose  $\beta$  such that

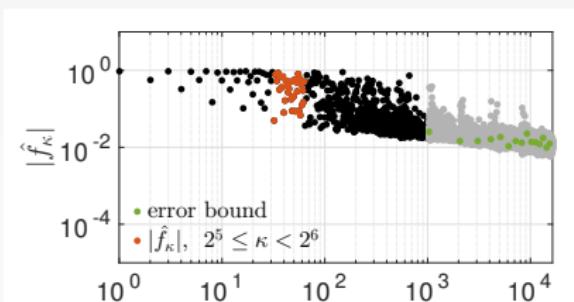
$$\sum_{\kappa=\lfloor b^{m-1} \rfloor}^{b^m-1} \left| \hat{f}_\kappa - \beta \hat{g}_\kappa \right| \xrightarrow{m \rightarrow \infty} 0 \quad \text{faster than} \quad \sum_{\kappa=\lfloor b^{m-1} \rfloor}^{b^m-1} \left| \hat{f}_\kappa \right| \xrightarrow{m \rightarrow \infty} 0.$$

This choice is not necessarily

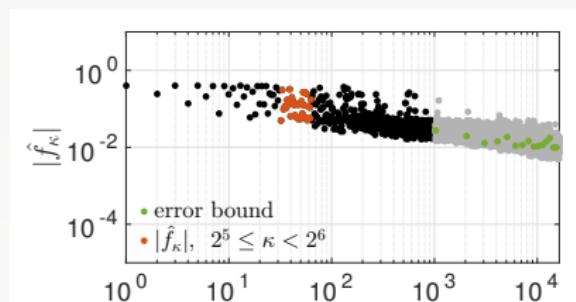
$$\beta = \frac{\text{cov}(f(\boldsymbol{X}), g(\boldsymbol{X}))}{\text{Var}(g(\boldsymbol{X}))} = \operatorname{argmin}_b \sum_{\kappa=0}^{\infty} \left| \hat{f}_\kappa - b \hat{g}_\kappa \right|^2,$$

as noted by Hickernell et al. (2005).

# American Option Walsh Coefficients: Control Variates



Cholesky (time differencing)



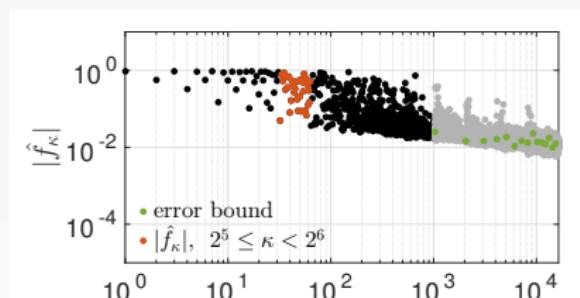
European put control variate

For  $\varepsilon = 0.05$ ,

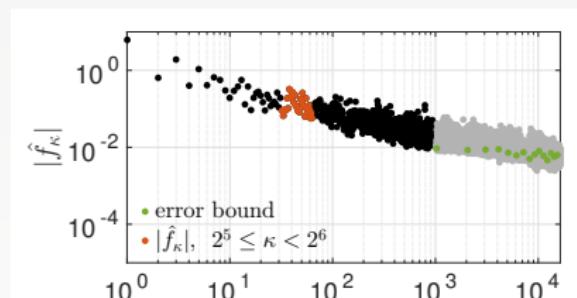
- ▶ 131,072 points and 3.12 seconds.
- ▶ 32,768 points and 0.75 seconds.



# American Option Walsh Coefficients: BM Construction



Cholesky (time differencing)



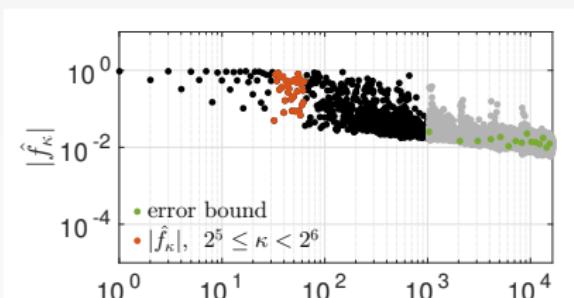
PCA

For  $\varepsilon = 0.05$ ,

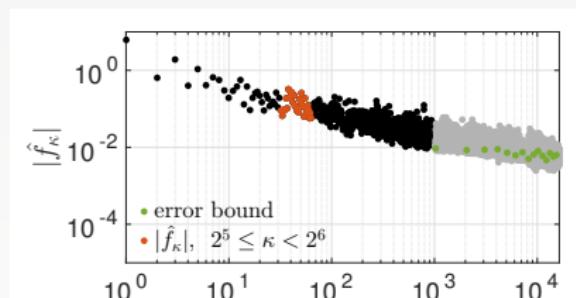
- ▶ 131,072 points and 3.12 seconds.
- ▶ 16,384 points and 0.44 seconds.



# American Option Walsh Coefficients: BM Construction



Cholesky (time differencing)



PCA

For  $\varepsilon = 0.05$ ,

- ▶ 131,072 points and 3.12 seconds.
- ▶ 16,384 points and 0.44 seconds.
- ▶ 8,192 points and 0.28 seconds.



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# Future Work

Additional capabilities,

- ▶ Cost from  $\mathcal{O}(n \log(n))$  to  $\mathcal{O}(n \log(n)^2)$ ,  $n = b^m$ .
- ▶ Allows for shifts and relative error tolerances.

Future work,

- ▶ Test the algorithm with rank-1 lattices.
- ▶ Apply multilevel quasi-Monte Carlo.
- ▶ Design adaptive cone conditions.
- ▶ Study other asset price models such as the Heston model.



## References I

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# Regression Basis

The basis proposed in Longstaff and Schwartz (2001) and used for our examples in our slides is:

- ▶  $e^{-\frac{x}{2S_0}}.$
- ▶  $e^{-\frac{x}{2S_0}}(1 - \frac{x}{S_0}).$
- ▶  $e^{-\frac{x}{2S_0}}(1 - 2\frac{x}{S_0} + \frac{x^2}{2S_0^2}).$



# Inside and Outside $\mathcal{C}$

